Abstract: It is good calibration practice to test thermocouples for homogeneity of the Seebeck’s coefficient during calibration process. If change in homogeneity the coefficient, commonly known as inhomogeneity is not detected, thermometer although calibrated might not be able to measure temperature correctly. Several different testing techniques are developed, depending on type of the thermocouple and the equipment available. In order to automate process of thermocouple inhomogeneity testing for all applicable testing methods a Thermocouple Inhomogeneity Testing Device was developed in Laboratory for Process Measurement (LPM), University of Zagreb. The device is mostly used for the testing of thermocouple inhomogeneity in conjunction with heater moving along the thermocouple. The sled for mounting of the heater or the thermometer is translated by a threaded shaft and a step motor in horizontal axis, vertical axis or its sliding direction can be tilted in six steps between those two positions. Sled is mounted on shafts guides with precision linear ball bearing, which allow for smooth translation. The frame of the device is designed with adjustable height and distance between legs, which allows testing in most available metrological baths or furnaces. System is controlled by custom made program on LabView platform, with ability to automatically acquire, store and analyze data test data. Variation of the thermovoltage recorded during measurement is used in calculation of the uncertainty of the calibration. This paper describes the techniques for inhomogeneity testing and design of the testing device. Interpretation of the measurement results and calculation of inhomogeneity related component of the uncertainty budget is presented.

Keywords: inhomogeneity testing, thermocouple.

1. INTRODUCTION

Seebeck’s coefficient of thermocouple wire is changing during prolonged use of thermocouple in elevated temperature, which may be main source of error in thermocouple temperature measurement [1]. Shock, mechanical deformation, radiation and other variables can also cause change in Seebeck’s coefficient of thermocouple wire. Thermoelectric emf is generated at zones with temperature gradients along thermocouple wire, i.e. along whole length of wire except segments which are in the isothermal zones. Level of generated emf is proportional to applied temperature gradient between cold and hot junction and to relative Seebeck’s coefficient in segment which passes through temperature gradient. Thus change in the local Seebeck’s coefficient in one segment of thermocouple wire may give wrong information about temperature level between cold and hot junction. Magnitude of error will depend on temperature profile along the thermocouple wire; only if segment of wire with degraded thermoelectric properties is in the isothermal zone, emf reading may be correct. Usually, this is not a case. Thermocouples are often used in different insertion depths, and there is little chance that non-degraded part of wire will be in isothermal zone which makes correct measurement with such thermometer impossible. Further, during routine calibration thermometers are inserted into calibration furnace at certain insertion depth. Temperature profile at calibration temperature could be very different from profile that occurs during regular use. If calibration furnace with large insertion depth is used significant variation of relative Seebeck’s coefficient may not be detected, because degraded area is kept isothermal. In such case, calibration certificate for degraded thermocouple may be issued in bona fide, with uncertainties which do not reflect physical state of the thermometer. In order to avoid inhomogeneity-related mistakes, a device was developed, which is used for testing of thermocouple inhomogeneity, as a part of their calibration procedure at LPM. Measured deviation of the generated thermovoltage is used for calculation of the inhomogeneity related uncertainty component for the calibration of the thermocouple. Device is designed on such manner that it allows testing of the thermocouple along most of it’s working length, while temperature gradient zone in which thermovoltage is generated can be of required length. Functionality of the device is further extended to all thermometric errands in LPM which require measurement of temperature distribution along some axis, such as thermometer immersion profiles and gradients in calibration baths and furnaces. The device is capable to running fully automated precision measurement at prescribed linear translation rates and sampling intervals. Tests can be done with displacement in vertical and horizontal direction.

2. METHODS FOR INHOMOGENEITY TESTING

Thermocouples are always tested for inhomogeneity defects on same basic principle regardless of the type of the thermocouple and the selected method. Temperature gradient is applied on part of the thermocouple wire and the thermovoltage is measured at the ends of the wires [2]. If difference between measured thermovoltage and expected
level of thermovoltage is not within tolerable margin for the type of the thermocouple and the testing method, thermocouple is considered to have became inhomogeneous. In calibration practice, tests of the single wire are seldom performed. Two methods are most commonly used for testing of inhomogeneity of thermocouples: moving temperature ramp and immersion test.

Temperature ramp testing method consists of moving two temperature gradients of opposite direction along the wire, while temperature at both ends is kept constant. Terminal emf measured at the end of the thermocouple is actually deference between emfs generated at both temperature gradients. In homogenous thermocouple those two emfs should cancel regardless of the shape of the temperature ramp. If temperature ramp is covering only small segment of thermocouple wire, like in “the traveling flame” test, generated emfs can also cancel since they were generated in adjacent regions where the Seebeck’s coefficient may be degraded by same amount. In such case thermocouple with a large segment of inhomogeneity may pass the test (properly nicked “fool’s test” [2], [3].

Immersion test is actually process during which thermocouple is gradually or in small steps immersed into temperature zone of high stability. Reading on the digital multimeter to which thermocouple is connected in that method is measure of relative Seebeck’s coefficient at the segment of the thermocouple which is subjected to temperature gradient. If transition zone between ambient temperature and temperature zone is very narrow, relative Seebeck’s coefficient of the small segment of the wire is examined. This is usually case when water, oil, salt baths or liquid nitrogen are used as temperature zones for inhomogeneity testing. On the other hand, when thermometer is being immersed in fixed point or calibration furnace, larger segment of the wire is subjected to temperature gradient. The temperature zone has to have temperature stability over test period at the level which would not produce significant effect on measured emf, since this could be reckoned as local inhomogeneity. When inhomogeneity is tested by insertion in fixed point stability is not a problem, otherwise monitoring thermometer must be used to estimate possible corrections. Inhomogeneity testing by immersion method at high temperature can add significant exposure time to high temperature (because inhomogeneity testing could last much longer than calibration), and in turn may impose risk of developing further inhomogeneity.

Design of the Testing device allows execution of the both methods of testing and selection of the method is based on following parameters: type of thermocouple, accumulated working hours, working depth of immersion, foreseen type of calibration and overall acceptable calibration costs. Most of the thermocouples are routinely tested with moving ramp method, for which the practice has shown is most economical in costs and time for everyday practice in the lab. Heaters of different lengths can be used for ramp method according to length of the segment which is suspected to be inhomogeneous, all in order to avoid test turning to fool’s test [2], [3]. Length may vary from 10 cm as default value to 20 cm for long industrial thermocouples. Tests are performed in vertical and tilted position, with cold and hot junction submerged in ice/water mixture, with rubber waterproof protection for ceramic insulated hot junction. Temperature of the heater is controlled in the range from 250 to 300°C. During test part of the thermocouple above the heater becomes hot because of the convection transfer from the heater, which makes second temperature ramp very broad. If exact location of inhomogeneity zone is needed, fan blowing across the heater is used to make two short ramps at the ends of the heater.

Thin metal sheathed mineral insulated (MIMS) thermocouples are tested by ramp method when used for regular (>250 mm) immersion measurements. In case where customer specify they are used in conjunction with popular small immersion dry block calibrators where only tip of the thermocouple is inserted into the thermal zone and there is sharp transition zone between working temperature and the environment, they are tested with gradual immersion into stabilized oil bath. This method allows accurate inhomogeneity evaluation of the short segment of wire in proximity of the hot junction of the thermocouple. Abovementioned methods are used for the thermocouples which are to be calibrated by comparison method. Thermocouples calibrated in fixed points are tested for inhomogeneity on traditional method by slow insertion into the fixed point.

3. TESTING DEVICE

Both methods require uniform motion of the thermocouple or a heater at predefined motion rate which may significantly vary, depending on thermocouple thermal capacity and type of the thermal source used. Furthermore, dependable and precision displacement control is required if testing of the thermocouple is to be left unattended. In order to meet those requirements the device was designed and manufactured at LPM. It can be used for immersion as well as for moving temperature ramp tests. System is designed around sturdy rectangular frame which allows motion of the sled with support for the heater or for the thermocouple. The sled is mounted on two large linear ball-bearings sliding on two shafts, and moved by spindle and stepper motor. The dedicated LabView program controls movements of the sled, as well as the acquisition and storage of the data from DMM to which thermocouple under test is connected.

The frame consists of two legs and inner frame on which the guide-shafts for the sled are mounted. Both legs and the inner frame are manufactured from stainless steel in order to sustain proximity of baths and furnaces. Two additional spacers can extend distance between the legs so that the frame can be positioned above thermometric baths or furnaces of different widths. Mounts for wheels are welded on the legs so that the device can be wheeled around the lab. Inner frame is mounted on the legs with four stainless steel screws, there are 26 holes along the legs’ height in 5 cm steps, and depending on the holes chosen to mount the inner frame, the distance between inner frame’s lowest point and a floor can vary between 0 and 130 cm. Furthermore the inner frame can be tilted in 15° steps from perpendicular to horizontal position by means of the perforated tilting plate.
with positioning holes distributed along its outer diameter.

The inner frame carries the stepper motor, the threaded shaft, and the holders for the shaft on which sled is guided. Distance between shaft holders allows for about 100 cm of working distance for the sled. The commercially obtained linear translation system consists of two shafts of 20 mm diameter, holders for the shafts, and large linear ball-bearings to which the box-shaped aluminum sled is attached. The linear system components assure low friction and stiffness and smooth running at desired rate at any position and in the translation range. Movement of the sled is implemented with threaded shaft connected to the stepper motor. Thermocouples and heaters are mounted on interchangeable supports, which are designed with adjustable clamp capable of receiving various types of thermometers. The design allows for two ways of fixing of the thermometer to the sled: rigidly (when used in a stirred baths or with moving heater), or flexibly, when thermometer is pushed or pulled by a sled but can displace in two lateral planes, as required for self aligning in, for example narrow bore of a furnace or a fixed point.

Control over stepper motor is achieved through custom-built control circuit. It is contained in separate box, which also contains transformer and rectifier for the circuit, switch for the step down transformer for the heater, potentiometer for the heater and stepper motors’s cooling fan and all the connectors and fuses to ensure tidy connection between PC and the device. Circuit itself is built with an Atmel AT89C2051 8-bit microcontroller and L297 stepper motor controller in combination with L298N bridge driver. Microcontroller has 2Kb of In-System Programmable Flash Memory, 15 programmable I/O lines, two 16-bit timer/counter, built-in serial peripheral interface for communication with PC and on-chip analog comparator. Microcontroller feeds step clock and direction signal to L297 stepper motor controller.

Controller integrates all control circuitry required to control bipolar and unipolar stepper motor, and generates signal for power driving circuitry. This combination was chosen because it has small number of components increases reliability and simplifies software development. Unipolar permanent magnet type stepper motor was chosen for drivetrain. It has nominal voltage 12.7 V, 12.5 W power rating, 48 steps per revolution which makes 7.5° step angle, holding torque of 240 mNm and maximum detent torque of 16 mNm. When used in conjunction with 10 mm threaded shaft with 1.5 mm pitch per revolution, the resulting drivetrain. It has nominal voltage 12.7 V, 12.5 W power rating, 48 steps per revolution which makes 7.5° step angle, holding torque of 240 mNm and maximum detent torque of 16 mNm. When used in conjunction with 10 mm threaded shaft with 1.5 mm pitch per revolution, the resulting

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It allows in burst mode manual positioning of the sled to specified height, then selection of the final position and the rate at which sled should be translated during test. Rate of translation is selectable in the range from 0.1 mm/min to 50 cm/min, reading of the current position, DUT’s emf at that position and the temperature of the heater (when used) are provided. Also selection of the thermocouple used for heater control is enabled. Selectable diagram allows on line analysis of the DUT’s output or heater temperature, and those data together with appropriate position of the sled can be stored. When used for applications other than inhomogeneity testing, program is used to select length and the rate of displacement of the sled.

4. TEST RESULTS

The purpose of the inhomogeneity testing is to detect possible inhomogeneity of the Seebeck’s coefficient of the thermocouple, and if detected quantitatively incorporate it into the uncertainty budget. Depending on the test results three scenarios are possible. When the thermovoltage deviation is found to be within uncertainty of the testing itself, the thermocouple is considered to have homogenous Seebeck’s coefficient. Uncertainty of the testing comprising mostly of the DMM uncertainty components is then used for inhomogeneity related component of the uncertainty budget.

In case when measured deviation of the thermovoltage is by it’s magnitude intolerable for this type of thermocouple, issue of the calibration certificate is denied. Customer is advised to discard this thermometer. En example of such testing is presented on Figure 4.

Thermocouple has outer diameter of 6 mm and the length of 700 mm and was not dismantled prior to the test. Heater with length of 100 mm and inner diameter 15 mm was used. Temperature of the heater during test was controlled to 270°C. Top 10 centimeters of the hot junction of the thermocouple were inserted in thin rubber protection sheath and immersed in ice/water mixture, as well as cold junction. Thermocouple was tested in vertical position with continuous rate of heater movement of 2 mm/min, from the hot junction of the thermometer toward cold junction. From results can be concluded that thermocouple is severely degraded through its length. At the start of the measurement lower, ascending temperature gradient, which is closer to the degraded tip of the thermometer, is very short, and as the heater moves along, it becomes wider and embraces segments with smaller degradation of local Seebeck’s coefficient. This explains the local maximum at 5 cm scanned length. As the heater progresses further, first ascending ramp is still in degraded zone, while descending ramp due to heat convection becomes wider and embraces zones closer to the cold junction where degradation of the local Seebeck’s coefficient is small, which causes decrease of measured emf.

In most cases outcome of the test will be between those two extremes. Deviation will be detected, it’s magnitude can be measured, and it inhomogeneity related component of the calibration uncertainty budget has to be calculated. When thermometers are calibrated at fixed points, calculation of uncertainty components emanating from inhomogeneity is straightforward. Since thermovoltage deviation is measured at the temperature of calibration by withdrawing thermometer from the thermometer well, difference of the thermovoltages at the bottom of the well and at 5 cm from the bottom is taken to be span of the rectangular distribution. Standard deviation is calculated simply by dividing value by square root of three.

When the moving ramp method is used, thermocouples are tested at the single temperature. For short MIMS thermocouples temperature of the stabilized oil bath is 100°, while temperature of the heater is in the range 250 - 300°, which is upper limit before any additional harmfull efect on thermocouple will take effect. The errors that would be induced due to inhomogeneity are both proportional on Seeback’s coefficient degradation and temperature gradient, meaning that for the same thermocouple on lower temperature error would be proportionally smaller than on higher temperature.
As the authors were not aware of any written recommendations for calculation of the standard deviation in moving ramp method, simple proportional method is used. For the part of temperature related errors, as rule of the thumb is accepted that probable thermovoltage deviation on higher temperatures would be proportionally higher, i.e. deviation on the 900°C would be three times higher than that measured on 300°C. Thermovoltage deviation calculated on this way is taken as range of rectangular distribution, and standard deviation is calculated by dividing that value by square root of three. Method is considered to be a bit conservative, and is used until more accurate investigations are carried out. An example is of uncertainty budget is presented in the table 1. Ceramic sheated Type K thermocouple was tested for the inhomogeneity and deviation was found to be in the range 20 microK. Temperature of the heater was at 270°C. In order to assess inhomogeneity at the calibration point of 660°C, the value of measured deviation at 270°C is multiplied by factor 2.4. Calculated value is than taken as range of the rectangular distribution and standard deviation is calculated by dividing with square root of three.

**CONCLUSION**

Testing of the thermocouples for inhomogeneity is important part of good calibration practice. Tests are mostly conducted with the heater installed on the sled. The results obtained from the inhomogeneity tests are used for quantification of the inhomogeneity uncertainty component to the overall calibration uncertainty. In some cases the testing can prevent the unnecessary calibration effort when the severe inhomogeneity is detected. The Thermocouple Inhomogeneity Testing Device designed for this purpose has proved to be useful and time saving tool in thermocouple testing. The device is also used in profiling axial temperature gradients in equalizing blocks for comparison calibration of the thermocouples and PRTs. Further application in which the device will be used is investigation of hydrostatic head effect profile in fixed points. Also further investigation in calculation of the standard deviation for the ramp method is planned.

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**REFERENCES**

