A magnetic current sensor with SQUID readout

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Abstract – A cryogenic magnetic current sensor has been constructed and tested for operation and sensitivity in the ac regime. The sensor is based on a ferromagnetic-core current transformer, coupled to a superconducting-quantum-interference-device (SQUID) current detector. The SQUID electronics provides a voltage output that can be coupled to room temperature signal recovery electronics, such as a lock-in amplifier. Working in liquid helium (4.2 K) the sensor transresistance is about 1.8 MΩ in the audio frequency range; the equivalent input current noise of the sensor, at the frequency of 1 kHz, is a few pA Hz⁻¹/² per unit primary winding turn. A major contribution to the detector noise is the thermal noise of the ferromagnetic core; however, an important excess noise contribution at low frequency is also present. The experiment is intended as a feasibility test towards the realization of high-sensitivity electromagnetic devices, such as current comparators, to be employed in primary current and impedance metrology setups working in the audio frequency range.

I. INTRODUCTION

The application of magnetic sensing of electrical currents is ubiquitous in test and measurement applications [1, 2]. In the field of electrical metrology, current transformers and current comparators allow the precise measurement of both dc and ac currents and of current ratios, and constitute a pillar of electrical impedance metrology [3, Sec. 4.5].

Current comparators (CC) [4] are the most accurate current ratio standards available. They reach uncertainties better than parts in 10⁶, both in dc and in the audio frequency range. In a CC, a ferromagnetic core defines a closed flux path of high permeability \( \mathcal{P} \). The currents \( I_k \) to be compared flow through windings of \( n_k \) turns, linked to the core. The resulting magnetomotive force \( \mathcal{M} = \sum n_k I_k \) generates a magnetic flux \( \Phi = \mathcal{P} \mathcal{M} \). In the ac regime, \( \Phi \) is sensed by a suitable detection winding, connected to the input of a front-end amplifier and signal-recovery electronics. In the dc regime, \( \Phi \) is sensed with fluxgate techniques [2, 5]. If the condition \( \Phi = 0 \) occurs, then \( \sum n_k I_k = 0 \), and the current ratio is equal to the turns ratio.

The sensitivity of a CC is limited by the noise occurring in the detection of the condition \( \Phi = 0 \). If the noise of \( I_k \) can be neglected, the detection noise is caused by the spontaneous fluctuations of \( \Phi \) in the ferromagnetic core employed, and by the noise of the signal conditioning electronics (which is in turn typically associated with that of its front-end amplifier). A CC working in a cryogenic environment benefits of a reduction of all noise contributions caused by thermal fluctuations, and of the possibility of using the extremely sensitive superconducting-quantum-interference devices (SQUID) as flux detector.

We realized a cryogenic magnetic current detector provided with a SQUID front-end electronics. The paper reports on measurements performed with the detector and its noise in the audio frequency bandwidth. The experiment is to be intended as a feasibility test towards the realization of a cryogenic current comparator (CCC; see [6] and references therein) working in ac regime [7–12].

II. EXPERIMENTAL

A schematic view of the experimental system is shown in Fig. 1.

A small 1 : 1 current transformer is constructed with a primary and a secondary winding, both having 1 turn, and made of non-superconducting metal (enameled copper) wound on a ferromagnetic core. Actually, two equal cores (Vacuumschmelze VITROPERM 500 F, model T6006-L2016-W403-04 toroidal core, 16 mm outside diameter, 10 mm inside diameter, 6 mm height) have been employed, wound in opposite directions in order to minimize the magnetic coupling with possible external magnetic interference sources. No superconducting shielding of the core or the windings has been employed.

The SQUID [13] is a wideband commercial model, a Magnicon 1-stage SQUID current sensor C6XXL1W. Its main specifications are:

- nominal input inductance \( L_{\text{SQUID}} = 1.8 \mu \text{H} \);
- input coupling \( 1/M_{\text{in}} = 0.232 \mu \text{A} \Phi_0^{-1} \), where \( M_{\text{in}} = 8.914 \text{nH} \) is the mutual inductance between the input coil and the Josephson junction loop;
- transfer coefficient: \( V_\phi = 580.7 \mu \text{V} \Phi_0^{-1} = 280.8 \text{GHz} \)

¹The quantity \( \Phi_0 = \hbar/2e = 2.067 833 667(52) \times 10^{-15} \text{Wb} \) [14] is the magnetic flux quantum. \( \hbar \) is the Planck constant, \( e \) the elementary charge.
**Fig. 1. Schematic representation of the experiment. A voltage source $E$ and a high-valued resistor $R$ constitute a low current source $I_p$. The current is injected in the one-turn primary winding of the ferromagnetic current transformer. The secondary winding, having an output inductance $L_C$, is coupled to the SQUID input (having inductance $L_{\text{SQUID}}$). The magnetic flux generated by $I_S$ is coupled to the SQUID via the mutual inductance $M_m$. The SQUID is read by a sensitive integrative voltage amplifier, which output $V_{\text{out}}$ can be read by the lock-in amplifier or by a signal analyzer (not shown). The voltage $V_{\text{out}}$, through a feedback resistance $R_f$ and a feedback mutual inductance $M_f$, holds the flux in the SQUID to zero (within a multiple of the flux quantum $\Phi_0$).

- feedback sensitivity $1/M_f = 42.6 \mu A \Phi_0^{-1}$, where $M_f = 48.54 \mu H$ is the mutual inductance between the feedback coil and the Josephson junction loop;
- flux noise $S_{\Phi}^{\text{SQUID}} = 0.937 \mu \Phi_0 Hz^{-1/2} = 1.94 \times 10^{-22} Wb Hz^{-1/2}$ at the frequency of 1 kHz.

The SQUID is enclosed in a Nb superconducting capsule and is operated with its room-temperature electronics (Magnicon XXF-1), which achieves a 50 MHz open-loop bandwidth and a 20 MHz flux-locked-loop bandwidth.

The current transformer and the SQUID are mounted at the end of a cryogenic probe, provided with a magnetic shield made of a thin $\mu$-metal foil, and with coaxial leads to the room-temperature environment. The SQUID is constructed to allow cooling under the Earth magnetic field, and no further magnetic shielding has been found necessary for its proper working. A photo of the cryogenic probe head is shown in Fig. 2.

During operation, the probe is inserted in a liquid helium dewar at ambient pressure, reaching a working temperature $T = 4.2 \text{ K}$. The SQUID is operated in flux-locked-loop configuration (see the caption of Fig. 1), in order to achieve a linear response. A feedback resistance $R_f = 10 \text{ k}\Omega$ is employed during all experiments.

The primary winding can be fed with a test current $I_p$, generated with a commercial voltage waveform synthesizer $E$ and a high-valued resistor $R$ in series. $R$ has a nominal value of 10 $\Omega$ and has been calibrated in the audio frequency range. The secondary current $I_S \approx I_p$ is directly connected to the SQUID input. The voltage output of the SQUID electronics is measured either with a fast-fourier-transform (FFT) signal analyzer (Agilent mod. 34970A), or with a lock-in amplifier (Stanford Research mod. 830), phase-locked to the synthesizer with a reference signal.

**Fig. 2. Photo of the cryogenic probe head. On the left, the magnetic core with the primary and secondary windings, wrapped in Teflon tape. In the center, the SQUID, enclosed in a cylindrical Nb superconducting capsule fixed on a Teflon plate. The probe holder on the right is a stainless steel thin-walled tube, within all wirings to the room-temperature environment are located.

### III. RESULTS

**A. Transformer characterization**

The equivalent inductance $L_C$ and resistance $R_C$ per unit winding turn, has been determined at the working temperature $T = 4.2 \text{ K}$ by performing impedance measurements (with an $LCR$ meter) on a larger core of the same material, wound with 70 turns, and by scaling the measured values accordingly. At the center frequency of 1.592 kHz ($\omega = 10 \text{ kHz}$), $L_C \approx 56 \mu H$, which is mismatched to the specified SQUID input inductance $L_{\text{SQUID}} = 1.8 \mu H$. In order to further improve the potential sensitivity, fractional-turn loop techniques [15] could be considered in the future.
B. Signal detection

A first series of measurements has been performed by driving the system with a sinusoidal excitation $E$ and sampling the lock-in amplifier readings. Fig. 3 shows a time series of sampled magnitude readings of the lock-in amplifier at $f = 1.592 \, \text{kHz}$; during the acquisition, a current test signal $I_P = 100 \, \text{pA}$ is generated.

C. Gain and noise

A second series of measurements have been performed with the FFT signal analyzer connected to the SQUID electronics output. The FFT analyzer can perform gain/phase analysis, or spectral analysis.

The transresistance gain of the magnetic current sensor $G = V_{out}/I_P$ has been measured with the analyzer in correlation mode, using a white noise signal excitation for $E$. The result is shown in Fig. 4. At low frequency the cutoff is caused by the ac coupling of the electronic chain. Above the frequency cutoff around $100 \, \text{Hz}$, $G$ is approximately constant. Its value is consistent with the theoretical gain $G_{\text{SQUID}}$ of the SQUID sensor and its electronics, which can be calculated from its specifications as

$$G_{\text{SQUID}} = \frac{M_{in}}{M_{f}} R_l = 1.84 \, \text{M\Omega}. \quad (1)$$

The output voltage noise is measured with the FFT analyzer in spectrum analysis mode. Together with the measured gain $G(f)$, it is possible to estimate the equivalent current noise power spectral density $S_I(f)$ at the primary winding input, which is shown in Fig. 5.

IV. DISCUSSION

The sources of detection noise $S_I$ are:

- the flux noise of the ferromagnetic core. The equilibrium thermal noise caused by flux thermal fluctuations can be evaluated with the Johnson-Nyquist theorem [16–18] from electrical impedance measurements. One can write $S_{\text{th}}(f) = 4k_B T G_C(f)$, where $G_C$ is the equivalent conductance of the secondary winding. Fig. 5 shows the result of the calculation. The behavior of the thermal noise spectrum, and in particular its $1/f$ behavior at low frequencies, is consistent with previous observations, see e.g. [19].

- the intrinsic flux noise of the SQUID. It can be calculated as $S_{\text{SQUID}} = S_{\Phi} / M_{in} = 1.87 \times 10^{-13} \, \text{A Hz}^{-1/2}$, and can therefore can be considered negligible in this experiment.

- the noise of the SQUID electronics, of the FFT analyzer, the thermal noise of the wiring and of the electrical components connected to the primary winding, and the electromagnetic interferences from the outside. These contributions can be considered negligible in this experiment.

Fig. 5 allows to compare the measured $S_I$ with the calculated $S_{\text{th}}(f)$. The comparison shows that $S_I$ diverges from $S_{\text{th}}$ at low frequency, and an excess noise is present. Such behavior will be investigated in the future: a probable cause is the presence of slow relaxations toward equilibrium of the residual dc magnetization of the core.
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REFERENCES


